

# A Course on Inductive Game Theory 1

by Mamoru Kaneko, 2009 February 27

General Aim:

**Experiential origin/emergence of belief/knowledge** of a player about the structure of the game.

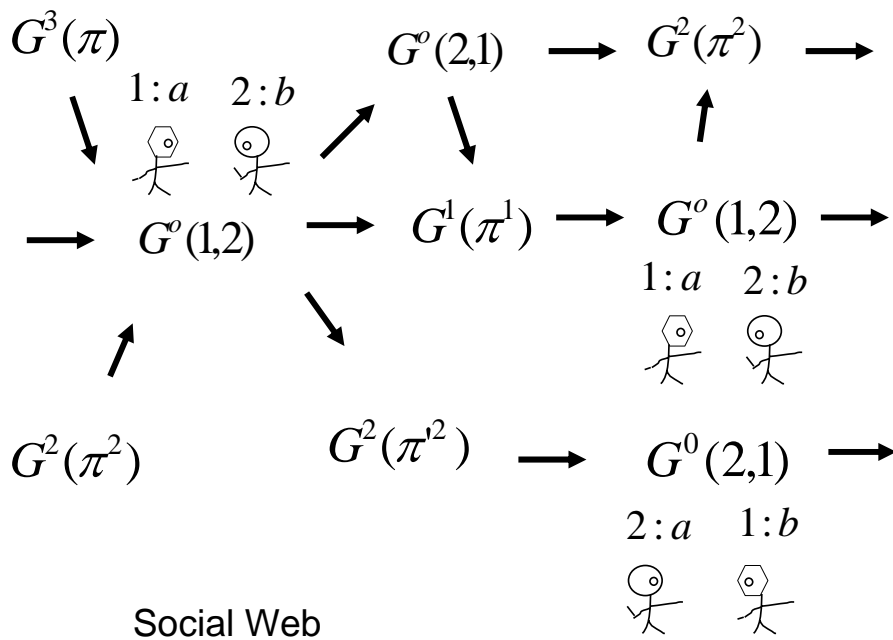
For this aim, first we should make:

0: the basic assumption that a player has little **knowledge of the structure** of the game.

Under this assumption, we should explore:

1. how can a player learn the structure from experiences?
2. in the first place, **what are experiences?**
3. how does he construct some view from experiences?
4. are his experiences enough to have a view?

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## Various Concepts need to be examined.

1. To learn the structure of the target situation, **repetition** of the target situation is required.  
Q1: Why not the **repeated game approach**?
2. The entire situation is formulated as a one-shot game and is considered from the ex ante point of view.  
Q2: Is anything wrong with this treatment?
3. A repeated game can be regarded as an extensive game.  
Q3: What is the status of an **extensive game theory**?
4. The theory of extensive games treats the problem of information in the most general manner in game theory.  
Q4: Are there any problems with this treatment of “**information**”?
5. An **information partition** describes **individual memory** in addition to **information transmission**.  
Q5: Is there any difficulty with this?
6. In game theory, the probabilistic behavior (mixed strategy) is assumed widely.  
Q6: Is this a sound assumption? First of all, what is “**probability**”?

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## Historical Background of Game Theory

1900~1910: Crises in  
Mathematics - - Russell's finding of a contradiction in Cantor's set theory  
Physics - - anomalies for relativity theory and quantum mechanics

↓  
**D. Hilbert**

↓  
**J. von Neumann**

↓  
Nash, Shapley,  
Shubik

↓  
Harsanyi, Aumann,  
Selten

- Minimax Theorem (1928)
- Gödel's Completeness Theorem (1930)  
Incompleteness Theorem (1931)
- Theory of Computation (1934~40)
- Gentzen's Proof Theory (1935)
- Neumann's Balanced Growth Model:  
Perfect Competition (1937)
- Wald's answer (1937) to von Mises's  
Frequentist Probability Theory
- Neumann's self-reproducing automata  
(1953-57)

### Reductionism since Harsanyi and Aumann

- Harsanyi (1955): Eliminating such differences, we have the common universal utility function:

$$u_i(x_i) \mapsto U(x_i, p_i)$$

the common utility function  $U(\cdot, \cdot)$

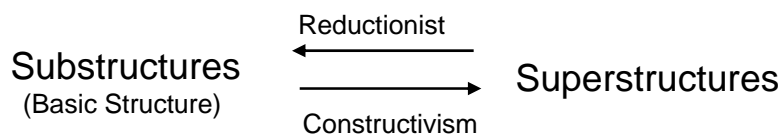
$$u_j(x_j) \mapsto U(x_j, p_j)$$

- Harsanyi (1967): Why people have different prior (probabilistic) beliefs?  
Because their experiences are different. There is still the common universal prior beliefs.
- Aumann (1976): each primitive state of the world contains all information.

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### Two Opposite Traditions

- Reductionism:  
We look for a more basic structure in a primitive element.



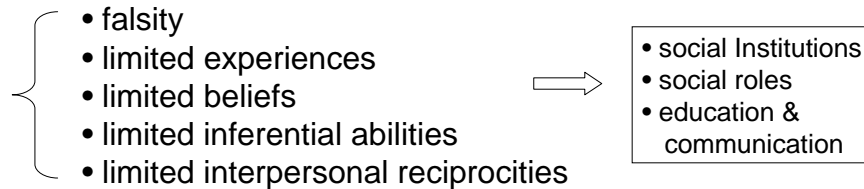
- Constructivism:  
We construct a superstructure on a less meaningful substructure (base).

Inductive Game Theory follows the tradition of constructivism and experientialism.

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## Implications from Inductive Game Theory

- Once the experiential source for individual belief/ knowledge becomes explicit, we can discuss various aspects of individual beliefs:



- We should change the **standard assumption** of game theory/ economics that a player is presumed to know the entire structure of the game.
- By this assumption, we are unable to understand the present “small and narrow” earth through game theory and economics.

- What is the status of perfect competition?
- Various assumptions of omniscience? → Page 18.

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## Von Neumann-Morgenstern (1944): 1

- Minimax Theorem for a 2-person zero-sum game;

$$G = (\{1,2\}, S_1, S_2, h_1, h_2)$$

- $h_1(s_1, s_2) + h_2(s_1, s_2) = 0$  for all  $(s_1, s_2) \in S_1 \times S_2$ .
- Maximin decision criterion :  
maximize the guarantee level of his payoffs :  $\max_{s_1 \in S_1} (\min_{s_2 \in S_2} h_1(s_1, s_2))$   
what is  $\min_{s_2 \in S_2} h_1(s_1, s_2)$ ?
- $(s_1^o, s_2^o)$  is a saddle point for  $h_1$  iff for all  $s_1 \in S_1$  and  $s_2 \in S_2$   
$$h_1(s_1^o, s_2) \leq h_1(s_1^o, s_2^o) \leq h_1(s_1, s_2^o).$$

Minimax Theorem : In the mixed extension  $\hat{G}$  of  $G$ ,

$$(1): \min_{s_2 \in \hat{S}_2} \max_{s_1 \in \hat{S}_1} \hat{h}_1(s_1, s_2) = \max_{s_1 \in \hat{S}_1} \min_{s_2 \in \hat{S}_2} \hat{h}_1(s_1, s_2);$$

(2): there is a saddle point for  $\hat{h}_1$  in  $\hat{G}$ .

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## Nash (1951)

- Nash equilibrium for an n-person game;  

$$G = (N, \{S_i\}_{i \in N}, \{h_i\}_{i \in N})$$
- $(s_1^o, s_2^o)$  is a Nash equilibrium iff for all  $i \in N$ ,  

$$h_i(s_i; s_{-i}^o) \leq h_i(s_i^o; s_{-i}^o) \text{ for all } s_i \in S_i.$$
- Nash Theorem: The mixed extension of  $G$  has a Nash equilibrium.
- Interchangeability: for all  $i \in N$ ,  
 if  $s$  and  $t$  are NE's, then  $(t_i; s_{-i})$  is an NE.
- Any 0 - sum 2 - person game has the interchanable equi.set.

The battle of the sexes is not solvable:  $\begin{pmatrix} (2,1) & (0,0) \\ (0,0) & (1,2) \end{pmatrix}$

Nash equilibrium is interpreted as an *Ex Ante* Decision Criterion <sup>9</sup>

## Von Neumann-Morgenstern (1944): 2

- Reduction of an extensive game to a normalized form:

An extensive form game

Kuhn's (1953) perfect recall condition supports this reduction



reduction

a strategy: a complete list of contingent actions

A normalized form game



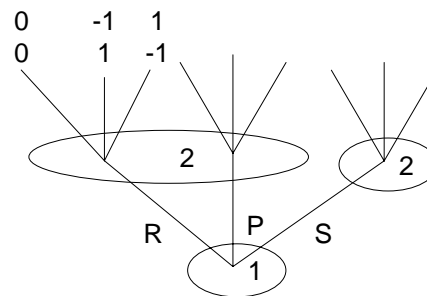
A characteristic function game:  
cooperative game  $(N, v)$   
+  
"stable set" + its interpretation.

- Cooperation is an axiom.
- Almost no substantive relations to the concepts of extensive games
- Almost 4 quarters are devoted to this concept

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### A Game in Extensive Form

1. Information?
2. Memory?
3. Strategy?



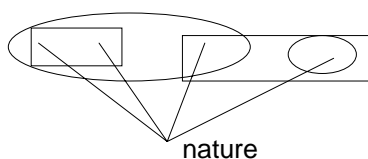
- **Merits** of an extensive game
  - Faithful representation of the rules of the game (society)
  - Interactions between information and actions
- **Demerits** of an extensive game
  - The viewpoint is unclear; objective or subjective?
  - Does an individual player captures the objective description?
  - Treatment of information and memory

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### Aumann's Information Partition Model

- $\Omega$ : the set of all possible states of the worlds;
- $p_i$  is a partition of  $\Omega$  for  $i = 1, 2$ , where if  $\omega \in \Omega$  occurs as the true state of the world, player  $i$  receives information  $p_i(\omega)$ .

$\omega \mapsto$  information  $p_i(\omega)$  :  
if  $p_i(\omega) \subseteq E \subseteq \Omega$ , then player  $i$  knows event  $E$ .



Simple extensive game:

- player 1's i.p.  $p_1$
- player 2's i.p.  $p_2$

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Difficulties found in Aumann's definition of common knowledge

An event  $E$  is common knowledge at the "true state"  $\omega_0$  iff

$$p_1(\omega_0) \subseteq E : \text{"1 knows } E\text{"}$$

$$p_2(\omega_0) \subseteq E : \text{"2 knows } E\text{"}$$

$$\forall \omega_1 \in p_1(\omega_0); p_2(\omega_1) \subseteq E : \text{"1 knows that 2 knows } E\text{"}$$

$$\forall \omega_1 \in p_2(\omega_0); p_1(\omega_1) \subseteq E : \text{"2 knows that 1 knows } E\text{"}$$

$$\forall \omega_1 \in p_1(\omega_0); \forall \omega_2 \in p_2(\omega_1); p_1(\omega_2) \subseteq E :$$

"1 knows, 2 knows 1 knows  $E$ "

• • •

- 1): the entire structure is known to the players
- 2): no distinction between "information" and "knowledge"
- 3): "Event" is the object of "information" or "knowledge".

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- Information partitions are, implicitly, assumed to be "common knowledge".
- Aumann (and his followers) adopts the reductionist view:

- $\omega$ : each primitive state of the world including the description of i.p.structures.

- This attitude comes from and is coherent in Savage's view and, more generally, probability theory.

- What is an alternative view to reductionism?

superstructures



substructures

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## What is "information"?

### Semantical way:

Information is expressed as a set of possibilities  $\{x_1, \dots, x_k\}$ .

### Syntactical way

Information is expressed as a proposition  $p$ .

### Connection?

This requires the back ground universal set  
universal set expressing possibilities.

$$\{x_1, \dots, x_k\} = \{x : p(x)\} ?$$

- \* This needs to choose a universal set.
- \*  $\{x_1, \dots, x_k\} = \{x \in X : p(x)\} ?$
- \* Is the empty information expressed as the entire set?
- \* Does rich information contains less contents?

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絶句

杜甫

江 碧 鳥 愈 々 白

山 青 花 欲 燃

今 春 看 々 又 過

何 日 是 歸 年

絶句 杜甫

江碧にして鳥愈々白く

山青くして花燃えんと欲す

今春 看々又た過ぐ

何れの日か 是れ帰年ならん

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## Constructions of Symbolic (mathematical) Logic

### 0: List of Pure Symbols:

- 01: propositional variables symbols:  $p_0, p_1, \dots$   
 02: logical connectives:  $\wedge$  (intended meaning, "and"),  $\vee$  (or),  $\supset$  (implies),  $\neg$  (not);  
 03: auxiliary symbols:  $(, )$

### 0: Rules to generate formulae (permissible expressions):

- 01: every propositional variable is a formula;  
 02: if  $A$  and  $B$  are formulae, so are  $(A \wedge B), (A \vee B), (A \supset B), (\neg A)$ ;  
 03: every formula is generated by a finite number of applications of 01 and 02.

## Gentzen-Style Sequent Calculus

### 0: Initial Sequents and Inference Rules:

- 01: Axioms:  $A \rightarrow A$ , where  $\rightarrow$  is an additional symbol.  
 02: Inference rules, e.g.,

$$\frac{A \rightarrow B}{C \wedge A \rightarrow B}$$

- Definition of a proof;
- Provability: Existence of a proof.

## Semantics in Symbolic Logic

A truth assignment is a function  $v: \{p_0, p_1, \dots\} \rightarrow \{t, f\}$ .

This is extended to the set of all formulae as follows:

- We define  $\models_v$  as follows :  
 0: for all propositional variable  $p$ ,  $\models_v p$  if and only if  $v(p) = t$ ;  
 1:  $\models_v \neg A$  if and only if not  $\models_v A$ ;  
 2:  $\models_v A \supset B$  if and only if not  $\models_v A$  or  $\models_v B$ ;  
 3:  $\models_v A \wedge B$  if and only if  $\models_v A$  and  $\models_v B$ ;  
 4:  $\models_v A \vee B$  if and only if  $\models_v A$  or  $\models_v B$ .

**Validity:** We write that  $\models A$  iff  $\models_v A$  for all truth assignments  $v$ .

**Completeness Theorem:** Validity is equivalent to Provability.

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## Various Hidden Assumptions of Omniscience

- Completeness-Soundness Theorem in logic:  
provability (existence of a proof)  
 $\longleftrightarrow$  validity (true for all possible models)
- Instantaneous Understanding;  
contents of an information piece can be extracted instantaneously.
- Instantaneous Utility Maximization;  
maximization of utility is instantaneously made.

More serious and similar omniscience assumptions are:

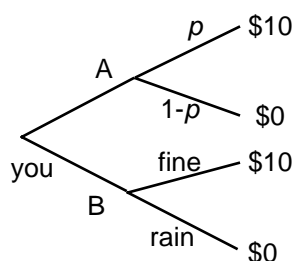
- a player knows the model which he lives in.
- he can make a plan over a long-horizon such as in the repeated game approach.

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## Use of "Subjective Probability"

- What is a subjective probability? (Savage ('54), Aumann-Anscombe ('61))  
Subjective belief? Degree of certainty for the subject?
- Both answers are simply changing the expressions.
- Real questions are: What does "degree of certainty for the subject" mean?

Any meaningful (experiential) definition of "subjective probability"?  
Now, what is the subjective probability of "tomorrow's fair weather"?



You choose either A or B.

Choice A: \$10 is given iff the well-designed random mechanism chooses "up" with probability  $p$   
Choice B: \$10 is given iff the weather is fine.

Changing  $p$  from 0 to 1, we find a  $p^*$  so that  $A(p^*)$  and B are indifferent.

Mathematically, completeness, continuity and monotonicity with respect  $p$  imply  $\exists p^*$ .

**Anything wrong?**

### von Neumann-Morgenstern (1944) (3)

$(N, v)$ : an  $n$ -person game in characteristic function form:

- $N = \{1, \dots, n\}$ ; the set of players;
- $v: 2^N \rightarrow R$  with  $v(\emptyset) = 0$ ; each value  $v(S)$  is the total amount of surplus that can be distributed among the players in  $S$ .

We say that  $x = (x_1, \dots, x_n)$  is an imputation iff

- $x_i \geq v(\{i\})$  for all  $i \in N$ ;
- $\sum_{i \in N} x_i = v(N)$ .

The set of all imputations is denoted by  $I$ .

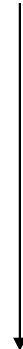
We say that  $x$  dominates  $y$  via coalition  $S$  iff

- $x_i > y_i$  for all  $i \in S$ ;
- $v(S) \geq \sum_{i \in S} x_i$ .
- This is denoted by  $x \text{ dom}_S y$ .

substructures



superstructures



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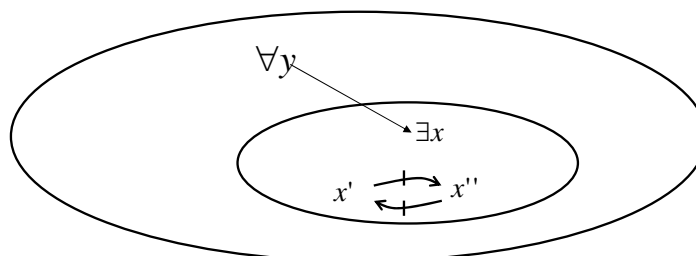
### von Neumann-Morgenstern (1944) (3)

We say that a subset  $V$  of  $I$  is a stable set in game  $(N, v)$  iff

- (External Stability): for any  $y \in I - V$ , there is a  $x \in V$  such that  $x \text{ dom}_S y$  for some  $S \in 2^N$ ;
- (Internal Stability): for any  $x, y \in I$  and  $S \in 2^N$ , it does not hold that  $x \text{ dom}_S y$ .



superstructures

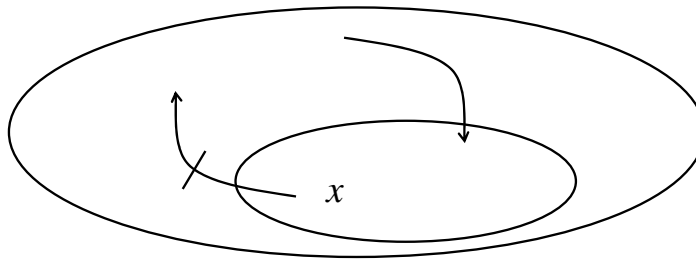


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## von Neumann-Morgenstern (1944) (3)

Interpretation of a stable set (Standard Behavior) :

- a triple  $\langle x; V, dom \rangle$
- $x \in V$  is a stationary state;
- $x$  continues to be a stationary state, which is supported by the internal and external stability conditions.



More basic postulate: the players know the structure of  $\langle V, dom \rangle$ , and then more substructures?

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A Course on Inductive Game Theory: References

Direct References (the first five papers are available at

<http://info.shakoku.ac.jp/~kaneko/>

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